

LECTURE 2

FINITE STATE MACHINES

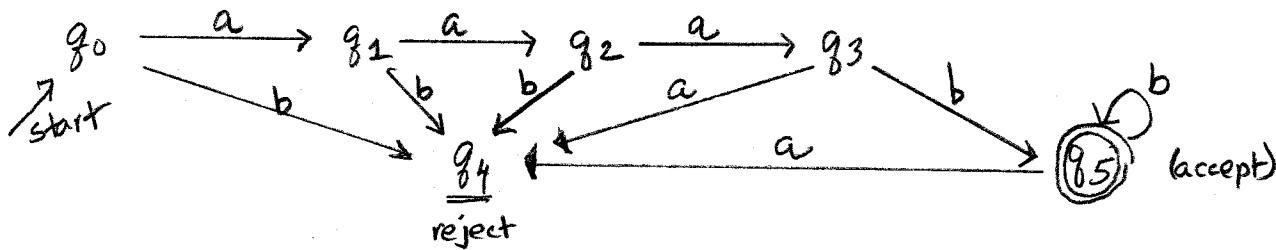
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Intuitive idea (deterministic machines)

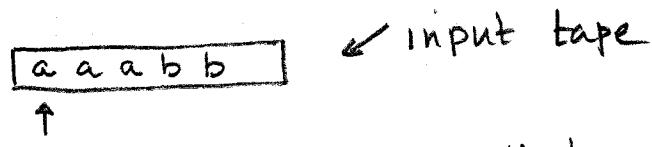
You want to "recognize" $a a a b^n \quad n \geq 1$

What kind of "machine" can do this?

Need to keep track of getting 3 a's and then an arbitrary number of b's.



Another view



CONTROL
UNIT

control unit keeps
track of "state" and
reads till the end of the tape

Note: control unit needs a finite # of states!

More generally (and still intuitively) look at the idea of input output behavior (I-O Behavior)



Without looking inside the box, we observe the I-O Behavior

Let X be the input alphabet, Y the output alphabet

The I-O Behavior is $R \subseteq X^+ \times Y^+$, i.e. $(x, y) \in R$

with $l(x) = l(y)$

$x = a_1 a_2 \dots a_n \rightarrow \boxed{\quad} \rightarrow y = b_1 b_2 \dots b_n$

\oplus	0	1
0	0	1
1	1	0

XOR
tableExample

Let the I-O relation be R^M such that:

$$(x_0 x_1 x_2 \dots x_n, y_0 y_1 y_2 \dots y_n) \in R^M$$

$$\text{iff for } t \geq 2 \quad y_t = x_{t-1} \oplus x_{t-2}$$

$x_0 x_1 x_2 x_3$

1 0 0 1

$y_0 y_1 y_2 y_3$

? ? 1 0

$x_0 \oplus x_1$

$x_1 \oplus x_2$

state is what allows the

determination of unique trajectories for the input.

This example machine can be viewed as having 4 states

$x_1 x_2$

0	0
0	1
1	0
1	1

Note: R^M is a "complete" behavior description. Experimentation can only determine a subset of R^M .

Formal Definition

A finite state (f.s.) sequential machine is a 6-tuple

$$M = \langle X, Y, Q, S, \lambda, q_0 \rangle \text{ where:}$$

X : is a finite set of inputs

Y : is a finite set of outputs

Q : is a finite set of states

q_0 : is the initial state

S : is a transition function $S: Q \times X \rightarrow Q$

(state transition)

λ : is the output function $(q, x) \mapsto q'$

$\lambda : Q \times X \rightarrow Y$ Mealy machine

$$(q, x) \mapsto y$$

$q_1 \xrightarrow{a/o} q_2$

$\lambda : Q \rightarrow Y$ Moore machine

$$q \mapsto y$$

$q_1 \xrightarrow{a} q_2$

Input sequence $x_0 x_1 \dots x_n$

$g_0 g_1 \dots g_n$

$y_0 y_1 \dots y_n$

$$\delta(g_i, x_i) = g_{i+1}$$

We define $\tilde{\beta}_{g_0} : X^+ \rightarrow Y^+$ extended behavior function from state g_0 .

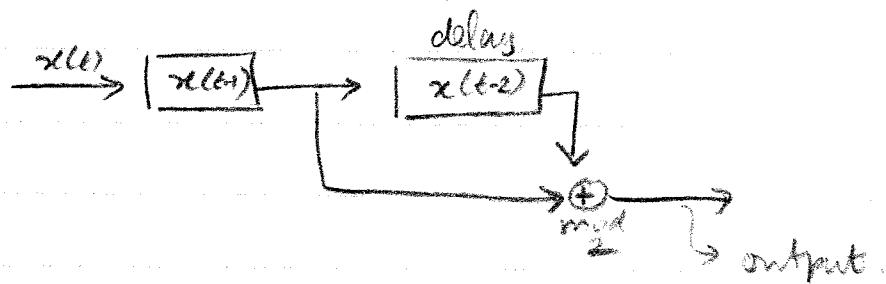
$$\text{by: } \tilde{\beta}_{g_0}(x_0 \dots x_n) = y_0 \dots y_n$$

Mealy where for Mealy: $y_i = \lambda(g_i, x_i)$

(if concerned with physical time) $y(t+1) = \lambda(g(t), x(t))$

Moore where for Moore: $y_i = \lambda(g_i)$

Realization of R^M defined earlier as Moore machine



$$x(t) \xrightarrow{\text{delay}} x(t-1)$$

$$Q = \{(0,0), (0,1), (1,0), (1,1)\}$$

1st delay, 2nd delay

$$Q = \{\hat{g}_0, \hat{g}_1, \hat{g}_2, \hat{g}_3\}$$

$$\lambda(\hat{g}_0) = 0 \quad \lambda(\hat{g}_2) = 1$$

$$\lambda(\hat{g}_1) = 1 \quad \lambda(\hat{g}_3) = 0$$

x	0	1	λ
\hat{g}_0	\hat{g}_0	\hat{g}_2	0
\hat{g}_1	\hat{g}_0	\hat{g}_2	1
\hat{g}_2	\hat{g}_2	\hat{g}_3	1
\hat{g}_3	\hat{g}_1	\hat{g}_3	0

$$\tilde{\beta} \hat{g}_1 (01001)$$

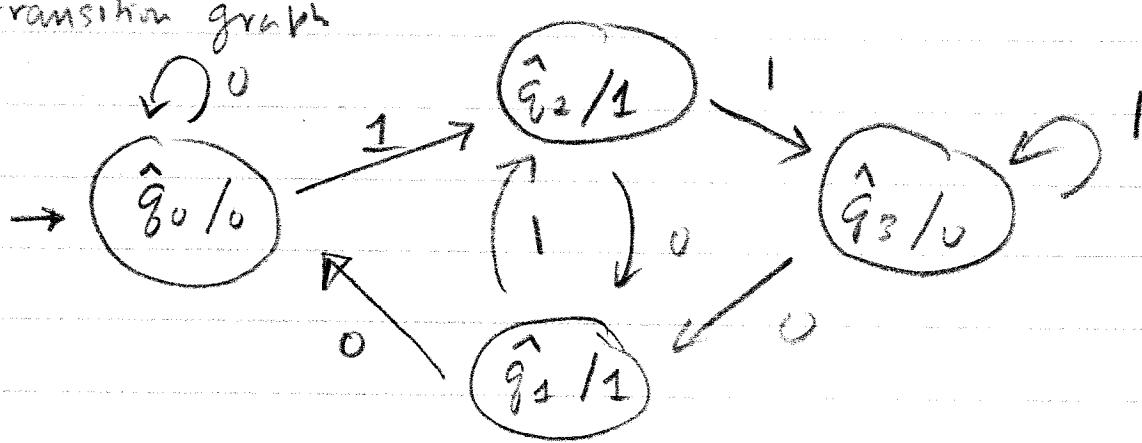
$$x_0 x_1 x_2 x_3 x_4$$

$$\hat{g}_1 \hat{g}_0 \hat{g}_2 \hat{g}_1 \hat{g}_0 \hat{g}_2$$

$$10110 \}$$

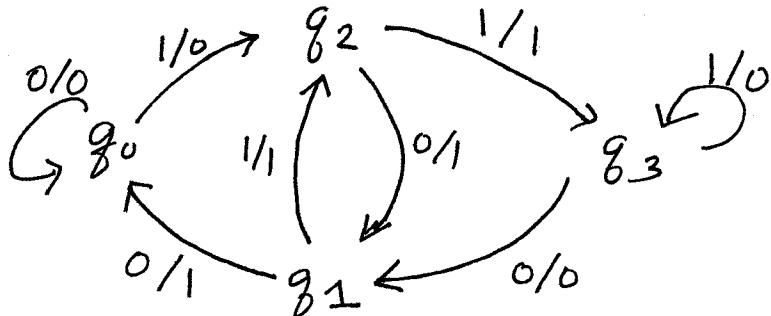
not used
for $\tilde{\beta}$

transition graph



Defining a Mealy Machine

$Q \setminus X$	0	1
g_0	$g_0/0$	$g_2/0$
g_1	$g_0/1$	$g_2/1$
g_2	$g_4/1$	$g_3/1$
g_3	$g_1/0$	$g_3/0$



$$\tilde{\beta}_{g_0}(111) = 010$$

$$\begin{matrix} x_0 & x_1 & x_2 \\ 1 & 1 & 1 \end{matrix} \quad \begin{matrix} g_0 & g_1 & g_2 & g_3 \\ g_0 & g_2 & g_3 & 010 \end{matrix} \quad \begin{matrix} y_0 & y_1 & y_2 \\ 0 & 1 & 0 \end{matrix}$$

Note that $R^M = \bigcup_{g \in Q} \tilde{\beta}_g$

M_1 is indistinguishable from $M_2 \Leftrightarrow R^{M_1} = R^{M_2}$

M_1 has the same behavior as M_2
 $\Leftrightarrow \{\tilde{\beta}_g \mid g \in Q_1\} = \{\tilde{\beta}_g \mid g \in Q_2\}$

Note : M_1 has same behavior as M_2

$\Rightarrow M_1$ indistinguishable M_2

Is the reverse of this statement true ?

Given a sequential machine $\langle X, Y, Q, q_0, \delta, \lambda \rangle$
 we define the extended transition function $\tilde{\delta}$ by:

$$\tilde{\delta} : Q \times X^* \rightarrow Q \text{ s.t.}$$

$$\tilde{\delta}(q, a) = \delta(q, a) \text{ for } a \in X$$

$$\tilde{\delta}(q, xa) = \delta(\tilde{\delta}(q, x), a) \text{ for } x \in X^+, a \in X$$

$$\tilde{\delta}(q, \lambda) = q$$

We define the extended output function $\tilde{\lambda}$ by:

Mealy

$$\tilde{\lambda} : Q \times X^+ \rightarrow Y \text{ s.t.}$$

$$\tilde{\lambda}(q, a) = \lambda(q, a) \text{ for } a \in X$$

$$\tilde{\lambda}(q, xa) = \lambda(\tilde{\lambda}(q, x), a) \text{ for } x \in X^+, a \in X.$$

Moore

$$\tilde{\lambda} : Q \times X^* \rightarrow Y \text{ s.t.}$$

$$\tilde{\lambda}(q, x) = \lambda(\tilde{\delta}(q, x)) \text{ for } x \in X^*$$

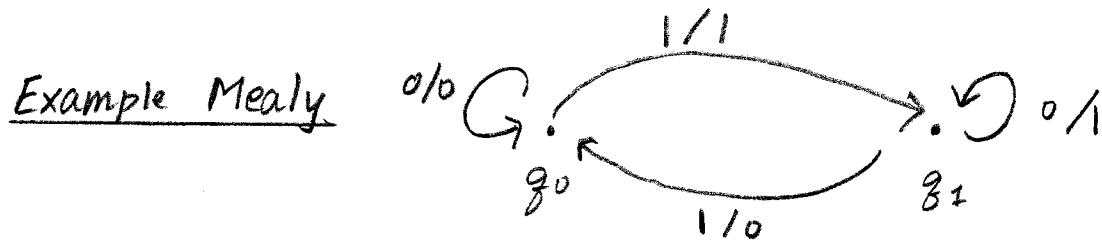
Defining the behavior function β_q from state q

Mealy $\beta_q : X^+ \rightarrow Y$ "output starting from state q , obtained on last transition"

$$\beta_q(xa) = \tilde{\lambda}(q, xa) \quad x \in X^*, a \in X$$

$\beta_q : X^* \rightarrow Y$ "output starting from state q , obtained from last state entered"

$$\beta_q(x) = \tilde{\lambda}(q, x) \quad x \in X^*$$



$$\beta_{g_0}(011010) = 1$$

$$\beta_{g_1}(011010) = 0$$

For Mealy we have: $\hat{\beta}_g(x_1 x_2 \dots x_n) = \beta_g(x_1) \beta_g(x_1 x_2) \dots \beta_g(x_1 x_2 \dots x_n)$

$$\hat{\beta}_{g_0}(011) = 010$$

$$\hat{\beta}_{g_0}(011010) = 010011$$

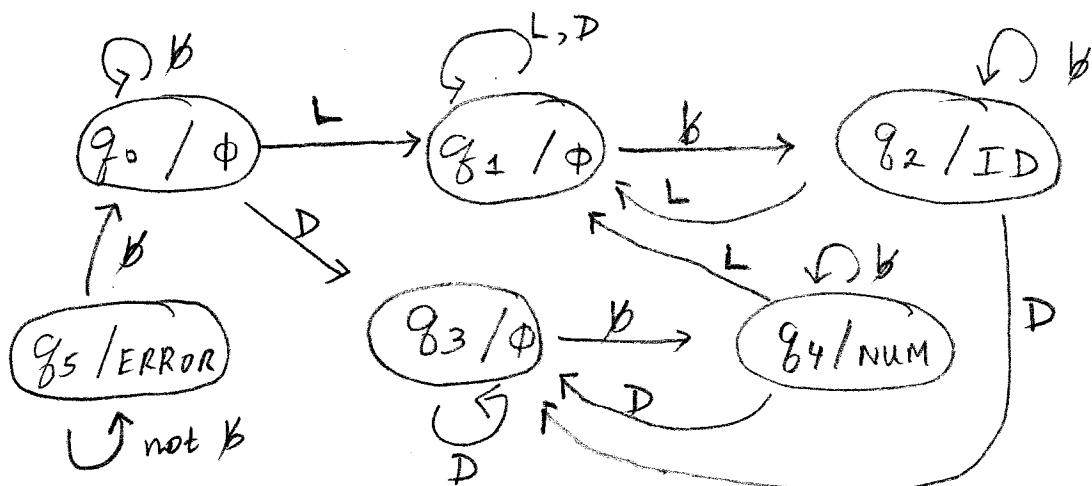
Example Moore

Let $L \triangleq A | B | C \dots | Z$ (letter)

$D \triangleq 0 | 1 | 2 \dots | 9$ (digit)

$\square, \text{blank} \triangleq \text{"blank"} \quad \sigma \triangleq \text{"other character"}$

Let $X = \{L, \square, \text{blank}, \sigma\}$ and $Y = \{ \phi, ID, NUM, ERROR \}$



All other transitions go to q_5 (error) from q_0, q_1, q_2, q_3, q_4

$$\beta_{g_0}(A25 \square \square) = ID$$

$$\beta_{g_0}(123 \square) = NUM$$

$$\beta_{g_0}(12?4) = ERROR$$

Note that for Moore we have:

$$\hat{\beta}_g(x_1 x_2 \dots x_n) = \beta_g(\lambda) \beta_g(x_1) \dots \beta_g(x_1 \dots x_{n-1})$$

we make sure length of input & output match.

Synthesis of Sequential Machines

Let $|X|$ be finite and $|Y|$ be finite

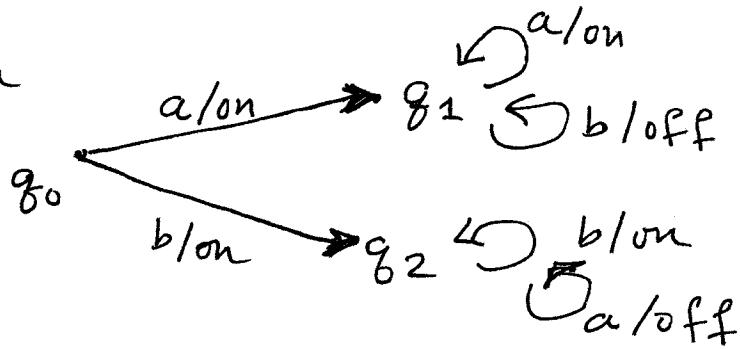
Given $f: X^+ \rightarrow Y$ we say that a Mealy machine M realizes f if there exists a state $g \in Q$ s.t. $\beta_g = f$

Example : A "blackbox" turns on the light if the first and last elements of a sequence are the same.

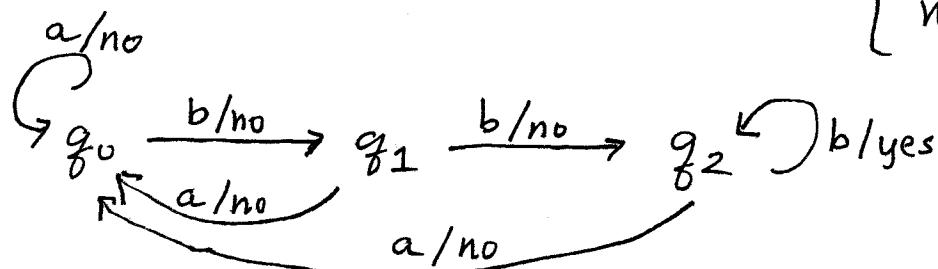
$$X = \{a, b\} \quad Y = \{\text{on}, \text{off}\}$$

$$f: X^+ \rightarrow Y \quad f(x) = \begin{cases} \text{on} & \text{if 1st \& last symbols same} \\ \text{off} & \text{otherwise} \end{cases}$$

Solution



Example $f: X^+ \rightarrow Y$ $f(x) = \begin{cases} \text{yes, if } x \text{ ends in } bbb \\ \text{no, otherwise} \end{cases}$

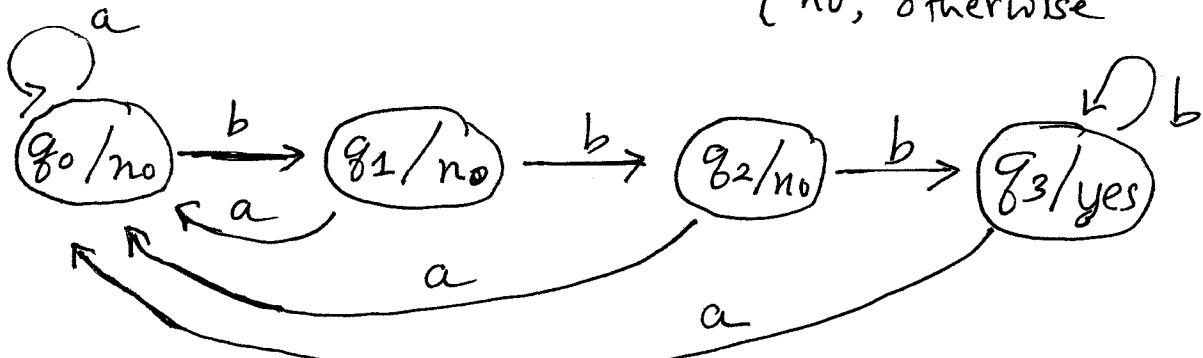


Synthesis for Moore Machines

$$f: X^* \rightarrow Y$$

Moore machine M realizes f if \exists state $g \in Q$
s.t. $\beta_g = f$

Example $f: X^* \rightarrow Y$ $f(x) = \begin{cases} \text{yes, if } x \text{ ends in } bbb \\ \text{no, otherwise} \end{cases}$

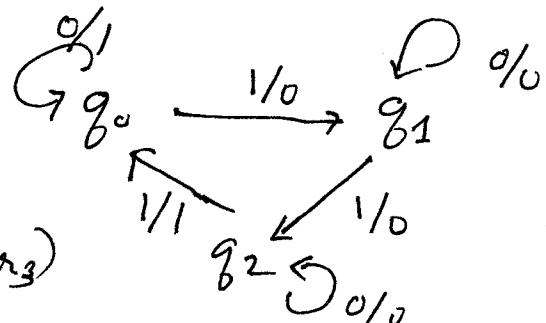
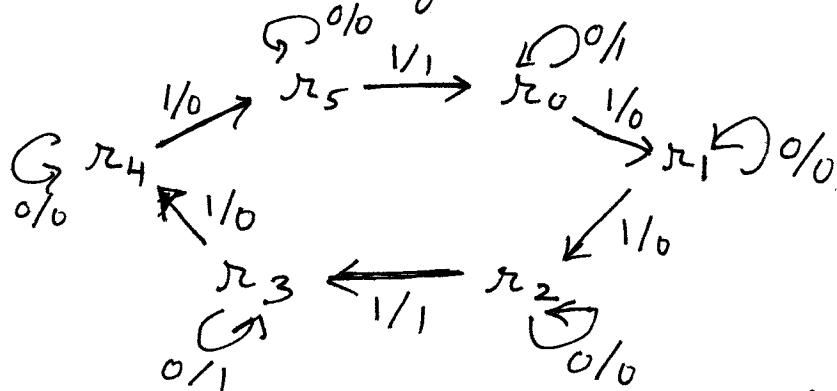


Equivalence of Machine Behaviors

Def. Let M and M' have state sets Q and Q' respectively
 g is equivalent to g' ($g \equiv g'$) if $\beta_g = \beta_{g'}$

Def $M \equiv M' \Leftrightarrow \{\beta_g \mid g \in Q\} = \{\beta_{g'} \mid g' \in Q'\}$

Example of equivalent machines



Note that

g_0 corresponds to r_0, r_3 ($g_0 \equiv r_0 \equiv r_3$)

Similarly $g_1 \equiv r_1 \equiv r_4$

$g_2 \equiv r_2 \equiv r_5$

Def M is reduced if $g \equiv r \Rightarrow g = r$
 alternatively M is reduced if $\beta_g = \beta_r \Rightarrow g = r$

Equivivalence Relation

Note that \equiv or $g \equiv r$ is an equivalence relation.

What is an equivalence relation? It is a relation R that satisfies three properties:

1. reflexive property $\forall x, (x, x) \in R$ or $x \equiv x$
2. symmetric property $x \equiv y \Rightarrow y \equiv x$
3. transitive property $x \equiv y$ and $y \equiv z \Rightarrow x \equiv z$

Example

$\text{mod } 5$ defines an equivalence relation on the integers

$$0 \equiv 5 \equiv 10 \equiv 15 \dots$$

$$1 \equiv 6 \equiv 11 \dots$$

$$2 \equiv 7 \equiv 12 \dots$$

Other examples

"in the same classroom" is an equivalence relation

"likes" is not an equivalence relation

Why is $g \equiv r$ an equivalence relation?

Easy to show using definition $\beta_g = \beta_r$

$\beta_g = \beta_r$ can be shown to be an equivalence relation.

$$\beta_g = \beta_g \quad \forall g$$

$$\beta_g = \beta_r \Rightarrow \beta_r = \beta_g$$

$$\beta_g = \beta_r \in \beta_r = \beta_s \Rightarrow \beta_g = \beta_s$$

Q



We often partition a set Q into partition classes Π_g, Π_r based on an equivalence relation $[g] = [r]$

Theorem For any machine M , there is a reduced machine M_R
s.t. $M \equiv M_R$

Proof Let $M = (X, Y, Q, S, \lambda)$

Define $M_R = (X, Y, Q_R, S_R, \lambda_R)$ as follows:

Let $Q_R = \{ [g] \mid g \in Q \}$ be the equivalence classes of Q
where $[g]$ is the set of states equivalent to g . That is:
 $g \equiv r$ if $\beta_g = \beta_r$.

Let $S_R : Q_R \times X \rightarrow Q_R$ by

$$S_R : ([g], a) \mapsto [S(g, a)]$$

Note that we must show this definition of S_R is well-defined!
That is, we need to show that if $g \equiv r$ then $S(g, a) \equiv S(r, a)$

Assume $g \equiv r$. Then $\beta_g = \beta_r$

$$\therefore \beta_g(ax) = \beta_r(ax) \quad \forall a \in X, x \in X^+$$

$$\therefore \beta_{S(g,a)}(x) = \beta_{S(r,a)}(x) \quad \forall x \in X^+$$

$$\Rightarrow [S(g, a)] = [S(r, a)] \text{ or } S(g, a) \equiv S(r, a).$$

An equivalence relation satisfying this transition
property is called right invariant.

We call also define

$$\lambda_R : Q_R \times X \rightarrow Y$$

$$([g], a) \mapsto [\lambda(g, a)]$$

(We need to also show that this function is well-defined)

We now claim that (1) $M \equiv M_R$

(2) M_R is reduced.

Proof

(1) $\forall g \in Q, \beta g = \beta_{[g]} \because M \equiv M_R$ (proof of part 1)

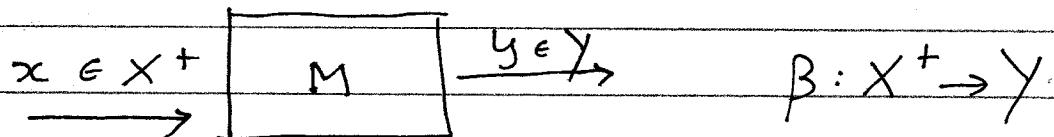
(2) Suppose $[g] \equiv [g']$, that is $\beta_{[g]} = \beta_{[g']}$

By definition $\beta g = \beta_{[g]} = \beta_{[g']} = \beta g'$

$\therefore g \equiv g' \text{ or } [g] = [g']$

This complete proof that for any M , there is a reduced machine equivalent to M .

Describing things behaviorally.



Can we capture the idea of "state"

Yes, state is "past history"!

Nerode Equivalence

Define an equivalence relation E_β on X^*

by $x E_\beta y \quad (x \equiv y)$

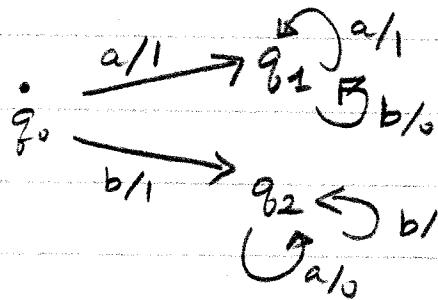
if $\beta(xz) = \beta(yz)$ for all $z \in X^+$.

We write $[x]_\beta$ for the equivalence class

Two input strings are equivalent if their "future behavior is the same."

Example $X = \{a, b\}$ $Y = \{0, 1\}$

$$\beta(x) = \begin{cases} 1 & \text{if 1st \& last symbols of } x \text{ the same} \\ 0 & \text{otherwise} \end{cases}$$



Partitioning X^*

$$[\lambda] = \{\lambda\}$$

$$[a] = \{x \mid x \text{ begins with } a\}$$

$$[b] = \{x \mid x \text{ begins with } b\}$$

Def If $\beta : X^+ \rightarrow Y$ then the Nerode machine of β is $M_\beta = (X, Y, Q_\beta, \delta_\beta, \lambda_\beta)$

$$\text{where } Q_\beta = \{[x]_\beta \mid x \in X^*\}$$

$$\delta_\beta([x]_\beta, a) = [xa]_\beta$$

$$\lambda_\beta([x]_\beta, a) = \beta(xa)$$

Can you prove this is well defined?

Use definition! Note will just write $[x]$ for $[x]_\beta$ if context is obvious.

Def: Let $l_x : X^+ \rightarrow X^+$ $x \in X^*$

$$\text{by } z \mapsto xz$$

Note: $\beta \circ l_x$ is a well defined function.

$$\beta \circ l_x(z) = \beta(l_x(z)) = \beta(xz).$$

Note

$$\beta_{[x]_\beta} = \beta \circ l_x \quad \text{Let } z = ya \quad a \in X, y \in X^*$$

$$\begin{aligned}\therefore \beta_{[x]_\beta}(z) &= \lambda_\beta(\tilde{\delta}_\beta([x]_\beta, y), a) \\ &= \lambda_\beta([xy]_\beta, a) \\ &= \beta(xya) = \beta(xz) = \beta \circ l_x(z)\end{aligned}$$

Theorem If M_β is the Nerode machine of β then

- (1) M_β realizes β .
- (2) M_β is reduced.

Proof (1) Consider state $[\lambda]$. $\beta_{[\lambda]} = \beta \circ l_\lambda = \beta$.

(2) Suppose $[x] \equiv [y]$

$$\begin{aligned}\Rightarrow \beta_{[x]} &= \beta_{[y]} \Rightarrow \beta(xz) = \beta(yz) \quad \forall z \in X^+ \\ &\Rightarrow x E_\beta y \Rightarrow [x] = [y].\end{aligned}$$

Note: $[x] = [y] \Leftrightarrow \beta l_x = \beta l_y$

Corollary.

A function $\beta: X^+ \rightarrow Y$ is finite state realizable
 $\Leftrightarrow E_\beta$ has a finite # of classes.

Def For $\beta: X^+ \rightarrow Y$, the machine of β is

$$M(\beta) = (X, Y, Q_\beta, \delta_\beta, \lambda_\beta)$$

$$Q_\beta = \{ \beta lx \mid x \in X^* \}$$

$$\delta_\beta(\beta lx, a) = \beta lxa$$

$$\lambda_\beta(\beta lx, a) = \beta(xa)$$

Similar to Nerode machine; just a different point of view. Looking at functions instead of equivalence classes of strings.

Myhill-Nerode

Theorem If $\beta: X^+ \rightarrow Y$ the the following are equivalent:

1. β is finite state realizable

2. E_β has a finite number of classes

3. $|\{\beta lx \mid x \in X^*\}| < \infty$ (ie. finite)

Example $X = Y = \{0, 1\}$, $\beta: X^+ \rightarrow Y$ $\beta(x) = \begin{cases} 1 & \text{if } \# \text{ 1's in } x \\ 0 & \geq \# 0's \text{ in } x \\ 0 & \text{otherwise} \end{cases}$

Not finite state realizable

z	$\beta(z)$	$\beta l_0(z)$	$\beta l_{00}(z)$	$\beta l_{000}(z)$	\dots
1	1	1	0	0	0
11	1	1	1	0	0
111	1	1	1	1	0
1111	1	1	1	1	1

etc.

" Infinite (ie. not finite) # of different functions βlx .

Algorithm for minimizing
state in a fs seq machine

Idea: find partition of state space that satisfies $\forall a \in X, \delta(q, a) \in \delta(r, a)$ ^{in same class} if q, r are in the same partition class.

Example	$Q \times X$	0	1	λ
	0	0	1	1
	1	1	2	0
	2	2	3	0
	3	3	4	1
	4	4	5	0
	5	5	0	0

1st partition by output λ . $\{0, 3\}, \{1, 2, 4, 5\}$
 states are distinguishable
 across classes

2nd, $\{1, 2, 4, 5\}$ splits. $\{0, 3\}, \{1, 4\} \{2, 5\}$

3rd. No more splitting all states in a class
 are indistinguishable (equivalent)

\therefore More precisely Machine reduction algorithm is.
 first partition states into $T\pi_2$ corresponding to outputs. Then find the coarsest partition that refines $T\pi_2$ and satisfies the SP property :

SP property : if $g \in r$ are in the same partition class, then for all $a \in x$, $\delta(g, a)$ and $\delta(r, a)$ are in the same partition class.

Note : this is an $O(n^2)$ algorithm. There is an $O(n \log n)$ algorithm for machine reduction, where n is the number of states.

	a_0	a_1	$T\pi_1 = T\pi_2$	a_0	a_2
<u>Example</u>	g_0	$g_2: 10$	$g_2: 11$	g_0	$g_2: 1$
	g_1	$g_3: 11$	$g_1: 0$	g_2	$g_2: 1$
	g_2	$g_2: 10$	$g_4: 11$	g_4	$g_4: 2$
	g_3	$g_3: 11$	$g_3: 10$	g_1	$g_2: 2$
	g_4	$g_3: 12$	$g_2: 10$	g_3	$g_3: 2$

	a_0	a_1
3. $g_0 \in g_2$ of class 1 in different class	-	-
8. g_4 in a different class from $g_4 \in g_3$	(1) g_0	-
	(2) g_2	-
	(3) g_1	$g_3: 3$
	g_3	$g_3: 3$
	(4) g_2	-

Done!

Shift attention to realization for
 f (or β) $f: X^* \rightarrow Y$

Example

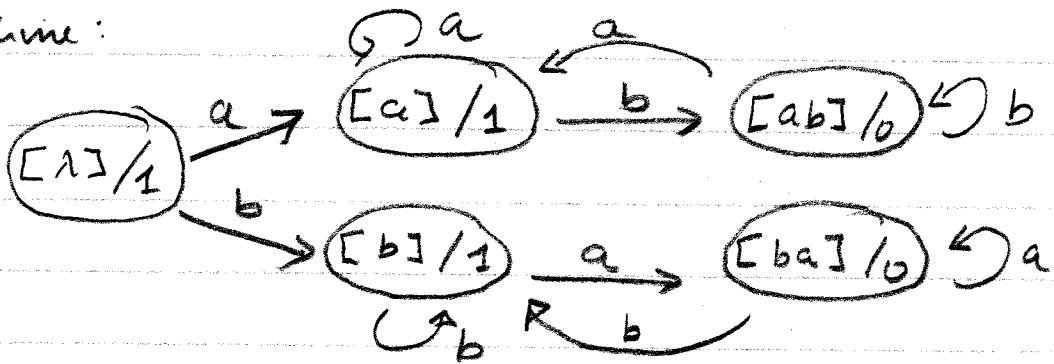
$$\beta: X^* \rightarrow Y \quad \begin{cases} 1 & \text{if 1st \& last symbol the same} \\ 0 & \text{otherwise} \end{cases}$$

Note: let $\beta(\lambda) = 1$

Nerode equivalence: $x \equiv y \Leftrightarrow \beta(xz) = \beta(yz)$ for $z \in X^*$

- \therefore classes are
- $[\lambda] = \{\lambda\}$
 - $[a] = \{x \mid x \text{ begins and ends with } a\}$
 - $[b] = \{x \mid x \text{ begins and ends with } b\}$
 - $[ab] = \{x \mid x \text{ begins with } a, \text{ ends with } b\}$
 - $[ba] = \{x \mid x \text{ begins with } b, \text{ ends with } a\}$

Moore machine:



Consider $\beta: X^* \rightarrow Y$. Let $Y = \{y_1, \dots, y_n\}$

Look at $\beta^{-1}(y_1), \beta^{-1}(y_2), \dots, \beta^{-1}(y_n)$.

Def: If $L \subseteq X^*$, then L is a finite state language if
 there exists a finite state Moore machine $M = \langle X, Y, Q, \delta, \gamma \rangle$
 s.t. $\beta_{\gamma}^{-1}(y) = L$ for some $g \in Q, y \in Y$.